

Matrix-Vector Multiplication

(Section 2.2)

Recall: how to show one vector is a linear combination of other, given vectors – we expanded all the operations, rewrote as a system of linear equations, then used a matrix to solve the system. We would like to go straight to the matrix!

Rewrite using Matrix-Vector Multiplication

Let \vec{v} be a vector in \mathbb{R}^n and

let A be an $m \times n$ matrix.

Let $\vec{a}_1, \vec{a}_2, \dots, \vec{a}_m$ denote the

row vectors of A , so

$$A = \begin{bmatrix} \vec{a}_1 \\ \vec{a}_2 \\ \vdots \\ \vec{a}_m \end{bmatrix} . \quad \text{Each } \vec{a}_i \text{ for}$$

$1 \leq i \leq m$ is a vector in \mathbb{R}^n , so

we can dot-product \vec{a}_i with v .

We then write the matrix - vector
product of A and \vec{v} by

$$A \cdot \vec{v} = \begin{bmatrix} \vec{a}_1 \cdot \vec{v} \\ \vec{a}_2 \cdot \vec{v} \\ \vec{a}_3 \cdot \vec{v} \\ \vdots \\ \vec{a}_m \cdot \vec{v} \end{bmatrix}, \quad a$$

vector in \mathbb{R}^m (each dot product is a real number, we have m of them).

Example 1:

Let $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$,

$$\vec{v} = \begin{bmatrix} -5 \\ 6 \end{bmatrix}.$$
 Compute

$$A \cdot \vec{v}.$$

Solution:

$$A \cdot \vec{v} = \left[\begin{bmatrix} 1 & 2 \end{bmatrix} \cdot \begin{bmatrix} -5 \\ 6 \end{bmatrix} \right] \\ \left[\begin{bmatrix} 3 & 4 \end{bmatrix} \cdot \begin{bmatrix} -5 \\ 6 \end{bmatrix} \right]$$

$$\rightarrow \begin{bmatrix} 7 \\ 9 \end{bmatrix}$$

Observations:

1) Dimension match: If A is an $m \times n$ matrix and \vec{v} is a $k \times 1$ vector, then the product

$A\vec{v}$ makes sense only when $n=k$.
 $(m \times n)$ $(k \times 1)$
↑ ↓ equal

The output $A\vec{v}$ is an $m \times 1$ vector.

2) Matrix columns: If A is an

$m \times n$ matrix, let \vec{e}_i in \mathbb{R}^n

be the vector

$$\begin{bmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

i.e. \vec{e}_1 is the vector with a 1 in the first entry, zeros in all other entries. What happens with the product $A \cdot \vec{e}_1$?

Example: $A = \begin{bmatrix} 2 & 1 & -5 \\ 6 & 0 & 3 \end{bmatrix}$

A is 2×3

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad 3 \times 1$$

$$A \cdot \vec{e}_1 = \underbrace{(2 \times 3) \times (3 \times 1)}_{\uparrow \downarrow} \left[[2 \ 1 \ -5] \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right] + \left[[6 \ 0 \ 3] \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right]$$

$$A \cdot \tilde{e}_1 = \begin{bmatrix} [2 & 1 & -5] \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \\ [6 & 0 & 3] \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \end{bmatrix}$$

$$= \begin{bmatrix} 2 \\ 6 \end{bmatrix}$$

the first
column of A

$$A = \begin{bmatrix} 2 & 1 & -5 \\ 6 & 0 & 3 \end{bmatrix}$$

In general, $A \cdot \tilde{e}_1 =$ the first column
of A

If \vec{e}_2 is the vector in \mathbb{R}^n with a one in the second entry, zeros in all other entries, then

$$A \cdot \vec{e}_2 = \text{the second column of } A$$

for our example,

$$\begin{bmatrix} 2 & 1 & -5 \\ 6 & 0 & 3 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} [2 \ 1 \ -5] \cdot [0] \\ [6 \ 0 \ 3] \cdot [0] \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \checkmark$$

If \vec{e}_3 is the vector in \mathbb{R}^n with
a 1 in the 3rd entry and
zeros in all other entries,

$$A \cdot \vec{e}_3 = \text{the third column of } A$$

In general, if e_k is the vector in
 \mathbb{R}^n with a 1 in the k^{th} entry
and zeros in all other entries,

$$A \cdot \vec{e}_k = \text{the } k^{\text{th}} \text{ column of } A$$

(there are n \vec{e}_k vectors in \mathbb{R}^n)

Example 2: Let T be the function
 that takes a vector $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$
 in \mathbb{R}^3 to the vector
 $\begin{bmatrix} x \\ y \\ 0 \end{bmatrix}$. Express T as a
 matrix.

Solution: Suppose A is the matrix that
 implements the function T ; that is,

$$A \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \\ y \\ 0 \end{bmatrix}$$

$(m \times 3) \quad 3 \times 1 \rightarrow 3 \times 1$

Find an explicit description of A .

$A\vec{e}_1$ = the first column of A .

But since $A\vec{e}_1 = A \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ is

Supposed to equal $\begin{bmatrix} x \\ y \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$,

the first column of A is $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$.

$$A(3 \times 1) = 3 \times 1$$

$\overset{\text{“}}{3 \times 3}$

Since A is 3×3 , we need two more columns.

$A\vec{e}_2 = \text{second column of } A$

$A\vec{e}_2 = A \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ is supposed to

equal $\begin{bmatrix} x \\ y \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$, so

the second column of A is $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$.

Finally, $A\vec{e}_3 = \text{third column of } A$,

$A\vec{e}_3 = A \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ is supposed to

equal $\begin{bmatrix} x \\ y \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$.

$$\begin{aligned} x &= z = 0 \\ y &= 1 \end{aligned}$$

$$x = y = 0, z = 1$$

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Is this correct?

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$= \begin{bmatrix} [1 0 0] \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} \\ [0 1 0] \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} \\ [0 0 0] \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} \end{bmatrix}$$

$$= \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

